Fast-Settling Low-Pass Filter Circuit



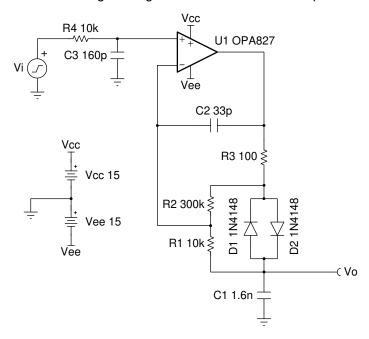
Design Goals

Input		Output		Supply	
V_{iMin}	V _{iMax}	V _{oMin}	V _{oMax}	V _{cc}	V _{ee}
–12 V	12 V	–12 V	12 V	15 V	–15 V

Cutoff Frequency (f _c)	Diode Threshold Voltage (V _t)	
10 kHz	20 mV	

Design Description

This low-pass filter topology offers a significant improvement in settling time over the conventional single-pole RC filter. This is achieved through the use of diodes D_1 and D_2 , that allow the filter capacitor to charge and discharge much faster when there is a large enough difference between the input and output voltages.



Design Notes

- 1. Observe the common-mode input limitations of the op amp.
- 2. Keeping C₁ small will ensure the op amp does not struggle to drive the capacitive load.
- 3. For the fastest settling time, use fast switching diodes.
- 4. The selected op amp should have sufficient output drive capability to charge C₁. R₃ limits the maximum charge current.



Design Steps

1. Select standard values for R_1 and C_1 based on $f_C = 10$ kHz.

$$R_1 = 10k\Omega$$

$$C_1 = \frac{1}{2\pi \times f_C \times R_1} = \frac{1}{2\pi \times 10 \text{kHz} \times 10 \text{k}\Omega} = 1.6 \text{nF}$$

2. Set the diode threshold voltage (V_t). This threshold is the minimum difference in voltage between the input and output that will result in diode conduction (fast capacitor charging and discharging).

$$V_{t} = \frac{V_{f}}{1 + \frac{R_{2}}{R_{1}}} \approx \frac{0.6V}{1 + \frac{R_{2}}{R_{1}}} = 20\text{mV}$$

$$R_2 = \left(\frac{0.6V}{20mV} - 1\right) \times R_1 = 290 k\Omega \quad \approx \quad 300 k\Omega \quad \text{(standard 5\% value)}$$

3. Select components for noise pre-filtering.

$$f_{c2} = 10 \times f_{c} = 100 \text{kHz}$$

$$f_{c2} = \frac{1}{2\pi \times R_4 \times C_3}$$

Select
$$R_4 = R_1 = 10k\Omega$$

$$C_3 = \frac{C_1}{10} = 160 pF$$

4. Add compensation components to stabilize U₁. R₃ limits the charge current into C₁ and also serves to isolate the capacitance from the op amp output when the diodes are conducting. Larger values will improve stability but increase C₁ charge time.

Select
$$R_3 = 100\Omega$$

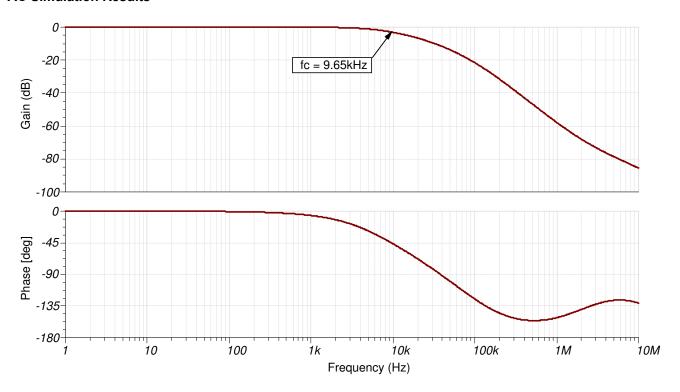
5. C_2 provides local high frequency feedback to counteract the interaction between the input capacitance with the parallel combination of R_1 and R_2 . To prevent interaction with C_1 , select C_2 as the following shows:

Select
$$C_2 = \frac{C_1}{50} = 32 \text{pF} \approx 33 \text{pF} \text{ (standard value)}$$

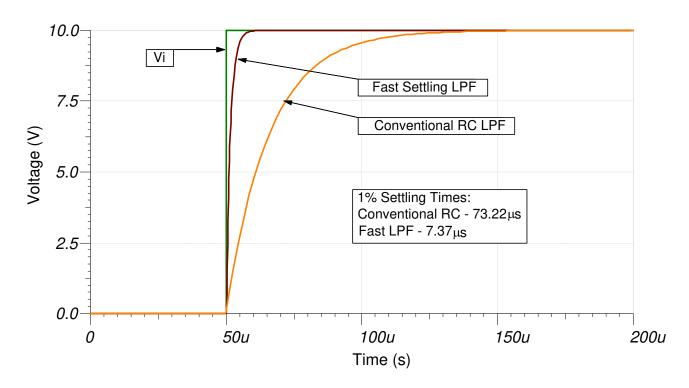


Design Simulations

AC Simulation Results



Transient Simulation Results



Design References

See Analog Engineer's Circuit Cookbooks for TI's comprehensive circuit library.

See TINA-TI™ circuit simulation file, SBOMAU1.

For more information on many op amp topics including common-mode range, output swing, bandwidth, and how to drive an ADC, see *TI Precision Labs*.

Design Featured Op Amp

OPA827				
V _{ss}	8 V to 36 V			
V _{inCM}	V _{ee} +3 V to V _{cc} –3 V			
V _{out}	V _{ee} +3 V to V _{cc} –3 V			
V _{os}	75 μV			
Iq	4.8 mA			
I _b	3 pA			
UGBW	22 MHz			
SR	28 V/µs			
#Channels	1			
OPA827				

Design Alternate Op Amp

TLC072				
V _{ss}	4.5 V to 16 V			
V _{inCM}	V _{ee} +0.5 V to V _{cc} -0.8 V			
V _{out}	V _{ee} +350 mV to V _{cc} -1 V			
V _{os}	390 μV			
Iq	2.1 mA/Ch			
I _b	1.5 pA			
UGBW	10 MHz			
SR	16 V/μs			
#Channels	1, 2, and 4			
TLC072				

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