

Performance Comparison between Two Automotive Knock Sensors



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Engine knock sensors are used to improve engine efficiency and performance by monitoring engine vibrations. The engine control unit (ECU) uses this data to adjust the fuel and air ratio to reduce “engine pinging” and correct the timing of the engine. TI’s [TPIC8101](#) serves as a signal conditioner for such engine knock sensors. Newer solutions sometimes integrate this functionality into one of the MCU’s in an engine’s ECU, however, this means that the processing might be done more remotely (due to the lower temperature grades of microcontrollers) which can degrade the signals. The [TPIC8101](#)’s performance can be validated by looking at how well the signal from the knock sensor is extracted compared to the noise of the system.

Brief Theory of Operation:

The [TPIC8101](#) performs the signal conditioning of knock sense elements, which are resonant piezoelectric sensor elements. After passing through input amplifiers, noise is filtered out of the signal with a band-pass filter centered on the center frequency of the sense element. The signal is then rectified and integrated. This output can then be transmitted either digitally or through an analog signal. The ECU monitors the strength of this signal to determine when a knock occurs.

Test Data:

This test data compares the [TPIC8101](#) and a competitor's device to show how the differences in band-pass filters affect the device performance and SNR. Both the TI device and competitor's device were configured the same way as shown in [Table 1](#).

Table 1. Test Settings

Byte	Data	Configuration	Value	Configured as
1st	0100 0110	Prescaler	11	8MHz
2nd	1110 0001	MUX	1	Ch2
3rd	0010 1001	BPF	41	6.94Khz
4th	1100 0000	Integration Time Constant	0	40uS
5th	1010 0010	Amplifier Gain	34	0.381

[Table 2](#) shows test data of the amplitude of the output signal with input signals of various frequencies. Each device's band-pass filter is programmed to have a center frequency of 6.94kHz, so input signals farther away from this center frequency should be rejected.

Table 2. Test Data

		Amplitude (V) at 1KHz	Amplitude (V) at 3KHz	Amplitude (V) at 6KHz	Amplitude (V) at 7KHz	Amplitude (V) at 8KHz	Amplitude (V) at 10KHz	Amplitude (V) at 50KHz
TPIC8101	Max	0.53	1.12	3.36	3.84	2.72	2.04	0.6
	Mid	0.4	0.76	1.84	2.32	1.84	1.4	0.47
	Min	0.34	0.68	1.44	1.84	1.36	1	0.4
Competitor's Device	Max	0.5	0.5	2.52	2.88	2.08	0.72	0.5
	Mid	0.3	0.25	1.16	1.6	1.22	0.06	0.2
	Min	0.04	0.04	0.56	1	0.48	0	0

The formula for SNR is:

$$SNR = 20 * \log\left(\frac{V_{signal}}{V_{noise}}\right) \tag{1}$$

[Figure 2](#) plots the results from [Table 1](#). The noise level () is approximately the same between the two parts because the amplitude far away from the center frequency is about the same. At the center frequency, the [TPIC8101](#) has a higher amplitude (meaning that its SNR is better than the competition).

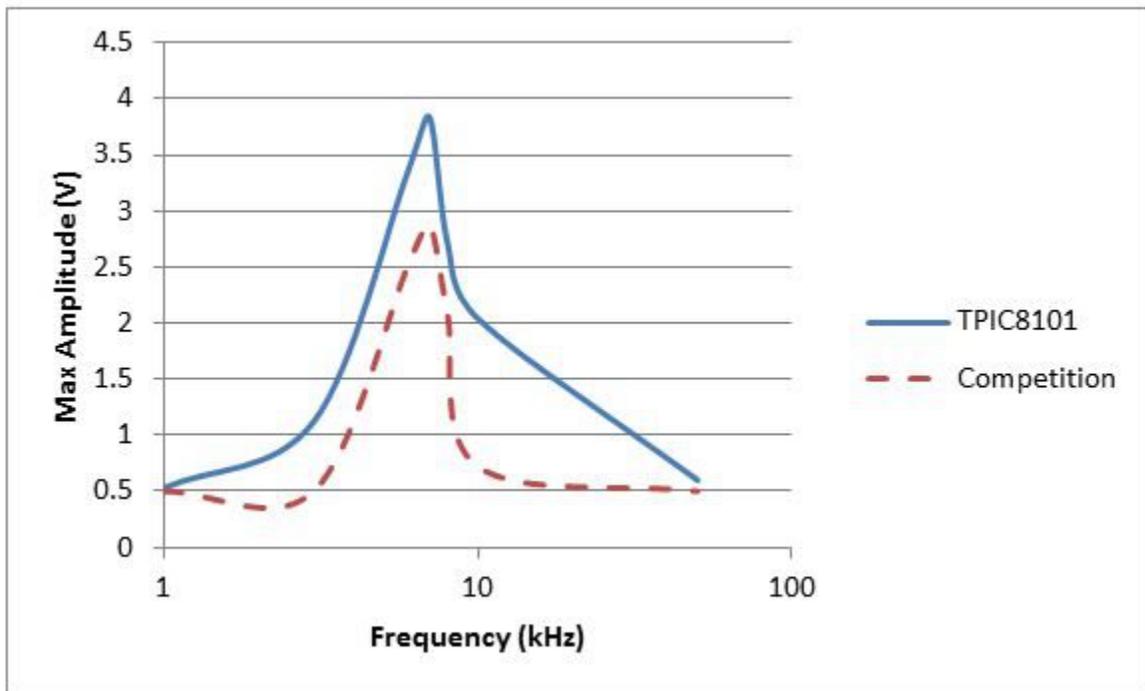


Figure 2. Test Results – Amplitude vs Frequency Comparison with Competition

Summary:

The band-pass filter is a critical component of the [TPIC8101](#). It is easily tested and can serve as a benchmark comparison between two similar devices. The test data shows that the [TPIC8101](#)'s band-pass filter rejects noise very well and compares favorably to competition.

See Also:

- [How to set-up a knock-sensor signal-conditioning system \(SLYT580\)](#)
- [Automotive Acoustic Knock Sensor Interface TI Design \(TIDA-00152\)](#)

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