# TLV320AIC20K/24KEVM

# User's Guide

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It is important to operate this EVM with a maximum input supply voltage not exceeding 4 V.

Exceeding the specified input range may cause unexpected operation and/or irreversible damage to the EVM. If there are questions concerning the input range, please contact a TI field representative prior to connecting the input power.

Applying loads outside of the specified output range may result in unintended operation and/or possible permanent damage to the EVM. Please consult the EVM User's Guide prior to connecting any load to the EVM output. If there is uncertainty as to the load specification, please contact a TI field representative.

During normal operation, some circuit components may have case temperatures greater than 30°C. The EVM is designed to operate properly with certain components above 40°C as long as the input and output ranges are maintained. These components include but are not limited to linear regulators, switching transistors, pass transistors, and current sense resistors. These types of devices can be identified using the EVM schematic located in the EVM User's Guide. When placing measurement probes near these devices during operation, please be aware that these devices may be very warm to the touch.

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## **Preface**

## **Read This First**

## **About This Manual**

This users guide describes the operation and use of the TLV320AlC20K codec family. A complete circuit description, schematic diagram, and bill of materials are also included.

## How to Use This Manual

Thi	s document contains the following chapters:
	Chapter 1—EVM Overview
	Chapter 2—Digital Interface
	Chapter 3—Analog Interface
	Chapter 4—EVM Operation
	Chapter 5—TLV320AIC20K/24K Bill of Materials
	Appendix A—TLV320AIC20K/24K Schematic

## **FCC Warning**

This equipment is intended for use in a laboratory test environment only. It generates, uses, and can radiate radio frequency energy and has not been tested for compliance with the limits of computing devices pursuant to subpart J of part 15 of FCC rules, which are designed to provide reasonable protection against radio frequency interference. Operation of this equipment in other environments may cause interference with radio communications, in which case the user at his own expense will be required to take whatever measures may be required to correct this interference.

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Data Sheet: Literature Number:

TLV320AIC20K/24K SLAS363

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# Chapter 1

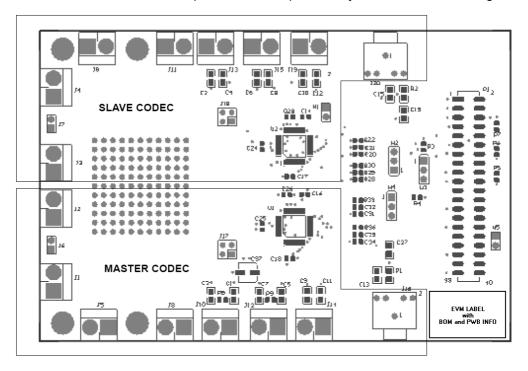
# **EVM Overview**

This user's guide provides support for the following EVMs:

- ☐ TLV320AIC20KEVM
- ☐ TLV320AIC24KEVM

Figure 1-1. EVM

The EVM is split into two complementary halves as shown in Figure 1–1.



## **Chapter 2**

# **Digital Interface**

The digital signals required to operate this codec originate from the 40-pin connector—J21. There are two methods to drive the digital interface:

- Create a custom interface between the codec EVM and the host system.
- □ Alternatively, if a TI DSK (DSP starter kit) is the host system, a development platform (AICDEVPLAT EVM) is available from TI. This platform provides the additional functions that the codec requires in a convenient form factor.

# Topic Page 2.1 Codec-to-Platform 2-2 2.2 Jumper Options 2-3

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## 2.1 Codec-to-Platform

The TLV320AlC20K and 24K mate with the development platform via a 40-pin Samtec connector. The mating connector (Samtec part number, TSM-120-01-T-DV-P) is used on the development platform to provide the electrical connections necessary. Consult Samtec at <a href="https://www.samtec.com">www.samtec.com</a> or 1-800-SAMTEC-9 for more information.

The pinout for the 40-pin connector is listed in Table 2–1.

Table 2-1. Pinout for 40-Pin Connector

J21.1 MCLK Master clock  J21.2 DGND Digital ground  J21.3 SCLK Serial data clock  J21.4 DGND Digital ground  J21.5 DIN Data in  J21.6 DGND Digital ground  J21.7 DOUT Data out  J21.8 Reserved Reserved for future use  J21.9 FS Frame sync  J21.10 Reserved Reserved for future use  J21.11 CLKX Transmit clock  J21.12 Reserved Reserved for future use  J21.13 FSX Frame sync transmit  J21.14 Reserved Reserved for future use  J21.15 DX Data transmit  J21.16 DR Data receive  J21.17 RESET Global reset for all devices	Number	Signal	Description
J21.3 SCLK Serial data clock  J21.4 DGND Digital ground  J21.5 DIN Data in  J21.6 DGND Digital ground  J21.7 DOUT Data out  J21.8 Reserved Reserved for future use  J21.9 FS Frame sync  J21.10 Reserved Reserved for future use  J21.11 CLKX Transmit clock  J21.12 Reserved Reserved for future use  J21.13 FSX Frame sync transmit  J21.14 Reserved Reserved for future use  J21.15 DX Data transmit  J21.16 DR Data receive	J21.1	MCLK	Master clock
J21.4 DGND Digital ground  J21.5 DIN Data in  J21.6 DGND Digital ground  J21.7 DOUT Data out  J21.8 Reserved Reserved for future use  J21.9 FS Frame sync  J21.10 Reserved Reserved for future use  J21.11 CLKX Transmit clock  J21.12 Reserved Reserved for future use  J21.13 FSX Frame sync transmit  J21.14 Reserved Reserved for future use  J21.15 DX Data transmit  J21.16 DR Data receive	J21.2	DGND	Digital ground
J21.5 DIN Data in  J21.6 DGND Digital ground  J21.7 DOUT Data out  J21.8 Reserved Reserved for future use  J21.9 FS Frame sync  J21.10 Reserved Reserved for future use  J21.11 CLKX Transmit clock  J21.12 Reserved Reserved for future use  J21.13 FSX Frame sync transmit  J21.14 Reserved Reserved for future use  J21.15 DX Data transmit  J21.16 DR Data receive	J21.3	SCLK	Serial data clock
J21.6 DGND Digital ground  J21.7 DOUT Data out  J21.8 Reserved Reserved for future use  J21.9 FS Frame sync  J21.10 Reserved Reserved for future use  J21.11 CLKX Transmit clock  J21.12 Reserved Reserved for future use  J21.13 FSX Frame sync transmit  J21.14 Reserved Reserved for future use  J21.15 DX Data transmit  J21.16 DR Data receive	J21.4	DGND	Digital ground
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J21.9 FS Frame sync  J21.10 Reserved Reserved for future use  J21.11 CLKX Transmit clock  J21.12 Reserved Reserved for future use  J21.13 FSX Frame sync transmit  J21.14 Reserved Reserved for future use  J21.15 DX Data transmit  J21.16 DR Data receive	J21.7	DOUT	Data out
J21.10 Reserved Reserved for future use  J21.11 CLKX Transmit clock  J21.12 Reserved Reserved for future use  J21.13 FSX Frame sync transmit  J21.14 Reserved Reserved for future use  J21.15 DX Data transmit  J21.16 DR Data receive	J21.8	Reserved	Reserved for future use
J21.11 CLKX Transmit clock  J21.12 Reserved Reserved for future use  J21.13 FSX Frame sync transmit  J21.14 Reserved Reserved for future use  J21.15 DX Data transmit  J21.16 DR Data receive	J21.9	FS	Frame sync
J21.12 Reserved Reserved for future use  J21.13 FSX Frame sync transmit  J21.14 Reserved Reserved for future use  J21.15 DX Data transmit  J21.16 DR Data receive	J21.10	Reserved	Reserved for future use
J21.13 FSX Frame sync transmit  J21.14 Reserved Reserved for future use  J21.15 DX Data transmit  J21.16 DR Data receive	J21.11	CLKX	Transmit clock
J21.14 Reserved Reserved for future use  J21.15 DX Data transmit  J21.16 DR Data receive	J21.12	Reserved	Reserved for future use
J21.15 DX Data transmit  J21.16 DR Data receive	J21.13	FSX	Frame sync transmit
J21.16 DR Data receive	J21.14	Reserved	Reserved for future use
	J21.15	DX	Data transmit
J21.17 RESET Global reset for all devices	J21.16	DR	Data receive
	J21.17 RESET Glob		Global reset for all devices
J21.18 FSR Frame sync receive	J21.18	FSR	Frame sync receive
J21.19 PWDN Global powerdown for all devices	J21.19	PWDN	Global powerdown for all devices
J21.20 CLKR Receive clock	J21.20	CLKR	Receive clock
J21.21 CNTLb GPIO pin	J21.21	CNTLb	GPIO pin
J21.22 CNTLa GPIO pin	J21.22	CNTLa	GPIO pin
J21.23 STATb Status pin	J21.23	STATb	Status pin
J21.24 STATa Status pin	J21.24	STATa	Status pin
J21.25 3.3V_D Digital 3.3 V	J21.25	3.3V_D	Digital 3.3 V
J21.26 Reserved Reserved for future use	J21.26	Reserved	Reserved for future use
J21.27 3.3V_D Digital 3.3 V	J21.27	3.3V_D	Digital 3.3 V
J21.28 DGND Digital ground	J21.28	DGND	Digital ground
J21.29 1.8V_D Digital 1.8 V	J21.29	1.8V_D	Digital 1.8 V
J21.30 DGND Digital ground	J21.30	DGND	Digital ground
J21.31 1.8V_D Digital 1.8 V	J21.31	1.8V_D	Digital 1.8 V
J21.32 DGND Digital ground	J21.32	DGND	Digital ground

Table 2-1. Pinout for 40-Pin Connector (Continued)

Pin Number	Signal	Description
J21.33	3.3V_A_DRV	Output driver supply 3.3 V
J21.34	J21.34 AGND Analog ground	
J21.35 3.3V_A_DRV		Output driver supply 3.3 V
J21.36 AGND Analog ground		Analog ground
J21.37	J21.37 3.3V_A Analog 3.3 V	
J21.38 AGND Analog ground		Analog ground
J21.39	3.3V_A	Analog 3.3 V
J21.40	AGND	Analog ground

The development platform supports a number of functions that the codecs require. These are:

MCLK generation
Manual reset generation
Power options

Refer to the *DSP – Codec Development Platform User's Guide* (TI Literature Number SLAU090) for details regarding the development platform.

Further descriptions regarding the operation of this EVM assumes that the development platform is being used for all additional signals and power.

## 2.2 Jumper Options

There are eight jumpers on the board that can be configured in various ways, depending upon the user's requirements. Their functions are briefly presented in Table 2–2:

Table 2-2. Jumper Options

Jumper	Function
W1	Gives users the option of disconnecting the 3.3-V driver ground from the regular analog ground
W2	Manages FSD from the master. Either connecting FSD to the next codec or providing relevant polarity
W3	Used along with W2 for correct polarity for FSD
W4 Selects whether U1 is either a master or a slave codec.	
W5	Connects analog and digital ground together
P1.9–P1.10	Last FSD in the chain must be high
P1.11-P1.12	SCL must be high
P1.13-P1.14	SDA must be high

Since the EVM contains two codecs, there a variety of options available to the user:

- ☐ Stand-alone slave codec
- Single master codec

Note that the terms master and slave refer to the codec device itself. Keep in mind that each of these codecs contains two independent channels connected together internally. Thus any codec configuration described in this guide actually comprises two individual codecs chained together and performing as one unit.

Each of these options are discussed in the following sections.

## 2.2.1 Stand-Alone Slave

This configuration applies to EVM1 only. When a single codec is to be used in slave mode, U1 is always the slave codec. Follow the jumper settings detailed in Table 2–3 for this condition.

Table 2-3. Stand-Alone Slave Jumper Settings

Jumper	1–2	2–3
W2	Inserted	Not inserted
W3	Not inserted	Inserted
W4	Not inserted	Inserted
P1.9–P1.10	N/A	N/A

## 2.2.2 Single Master Only

This configuration applies to EVM1 only. When a single codec is to be used in master mode, U1 is always the master codec. Follow the jumper settings detailed in Table 2–4 for this condition.

Table 2-4. Single Master Only Jumper Settings

Jumper	1–2	2–3
W2	Inserted	Not inserted
W3	Inserted	Not inserted
W4	Inserted	Not inserted
P1.9–P1.10	N/A	N/A

## 2.2.3 Master/Slave Cascade

This configuration applies to EVM1 only and is the factory-set shipping condition. When both codecs are used, both U1 and U2 are active. In this condition U1 is always the master codec, and U2 is always the slave codec. Follow the jumper settings detailed in Table 2–5.

Table 2-5. Master/Slave Cascade Jumper Settings

Jumper	1–2	2-3
W2	Not inserted	Inserted
W3	N/A	N/A
W4	Inserted	Not inserted
P1.9–P1.10	Inserted	Inserted

# **Chapter 3**

# **Analog Interface**

Table 3–1 indicates the applicable connectors for each codec. In order to enable a wide range of sources and loads to be connected to the codecs, screw terminals have been used wherever possible.

Table 3-1. Analog Interface Connectors

	TLV320	TLV320AIC20K TLV320AIC		AIC24K
	Master	Slave	Master	Slave
Input Sources				
8- $\Omega$ Speaker output	J2	J11	Not ava	ailable
600-Ω Line output	J5	J4	J5	J4
150- $\Omega$ Handset output	J1	J9	J1	J9
150- $\Omega$ Headset output	J8	J3	J8	J3
Output Loads				
Handset input/INP2	J12	J19	J12	J19
Headset input/INP3	J10	J13	J10	J13
Microphone input	J16	J20	J16	J20
Line input/INP1	J14	J15	J14	J15
Caller ID input/INP4	J17	J8	J17	J8

# **EVM Operation**

The EVM is shipped from the factory in master/slave cascade mode. To check if the EVM is working properly, simply install the EVM onto the development platform and apply power to the DSK. The EVM should begin working immediately.

In the default mode, the codecs recognize that there are four discrete channels, consequently the resultant SCLK and FS signals transmitted by the master codec adjust automatically based on the available MCLK.

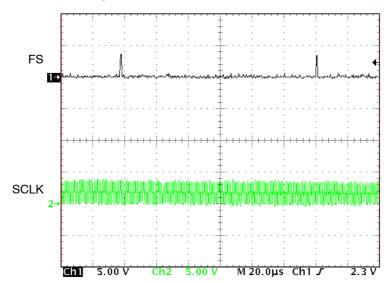
It is now possible to calculate what should be observed after power up by calculating what FS and SCLK should be observed:

- ☐ FS
  - In this example, MCLK is generated by the development platform and is equal to 100 MHz.
  - FS = MCLK/16  $\times$  m  $\times$  n  $\times$  p
  - Default values for m, n, and p are 16, 6, and 8 respectively
  - FS =  $100 \times 10^6 / 16 \times 16 \times 6 \times 8$
  - FS = 8138 kHz
- ☐ SCLK
  - $SCLK = 16 \times FS \times (number of devices) \times 2$
  - SCLK =  $16 \times 8138 \times 4 \times 2$
  - SCLK = 1.04 MHz

FS can be observed either directly at the FS pin of U1 or U2 (pin 19) or on the development platform at TP9. SCLK can be observed easily at P1 pin 3 of the EVM or on the development platform at TP8.

The captured signals are shown in Figure 4–1.

Figure 4–1. EVM Captured Signals



# TLV320AIC20K/24K Bill of Materials

The following table contains a complete bill of materials for the TLV320AlC20K/24K codec EVM. The schematic diagram is also provided for reference. Contact the Product Information Center or e-mail <a href="mailto:dataconvapps@list.ti.com">dataconvapps@list.ti.com</a> for questions regarding this EVM.

Used	Value	Ref Des	Description	Vendor	Part number
4	0.01 μF	C20 C29 C32 C34	Capacitor 10000-pF 50-V ceramic Y5V 0603	Panasonic	ECJ-1VF1H103Z
12	0.1 μF	C14 C16 C17 C18 C21 C23 C24 C25 C26 C28 C33 C35	Capacitor 0.1-μF 25-V ceramic Y5V 0603	Panasonic	ECJ-1VF1E104Z
16	0.1 μF	C1 C2 C3 C4 C5 C6 C7 C8 C9 C10 C11 C12 C13 C15 C19 C27	Capacitor 0.1-µF 50-V ceramic X7R 0805	Panasonic	ECJ-2YB1H104K
4	1 μF	C22 C30 C31 C36	Capacitor 1-μF 10-V ceramic Y5V 0603	Panasonic	ECJ-1VF1A105Z
1	10 μF	C37	Capacitor 10-μF 16-V VS elect SMD	Panasonic	ECE-V1CA100SR
7	10 kΩ	R3 R4 R5 R6 R7 R8 R9	Resistor 10-kΩ 1/16-W 5% 0603 SMD	Panasonic	ERJ-3GEYJ103V
2	10 kΩ	R1 R2	Resistor 10.0-kΩ 1/10-W 1% 0805 SMD	Panasonic	ERJ-6ENF1002V
2		U1 U2 *	IC CODEC dual-channel PROG LP 48-TQFP	Texas Instruments	TLV320AIC20KIPFB
	* Alternate		IC CODEC dual-channel PROG LP 48-TQFP	Texas Instruments	TLV320AIC24KIPFB
1			TLV320AIC20 PWB	Advanced Circuit Design	6442569
0			TLV320AIC20 DDB	Texas Instruments	6442568
1		J21	40-Pin SMT socket	Samtec	SSW-120-22-F-D-VS-K
1		P1	40-Pin SMT plug	Samtec	TSM-120-01-T-DV-P

Used	Value	Ref Des	Description	Vendor	Part number
14		J1 J2 J3	2 Terminal screw connector	Lumberg	KRMZ2
		J4 J5 J8			
		J9 J10 J11			
		J12 J13			
		J14 J15			
		J19			
2		J16 J20	161–3504	Mouser	161-3504
2		J17 J18	4-Pin plug	Samtec	TSW-102-07-L-D
4		J6 J7 W1	2 Position jumper	Samtec	TSW-102-07-L-S
		W5			
3		W2 W3 W4	3 Position jumper	Samtec	TSW-103-07-L-S
2		See Assy Dwg	1.000/4-40 Nylon hex thread SP	Keystone Electronics	1902E
2		See Assy Dwg	0.500/4-40 Nylon hex thread SP	Keystone Electronics	1902C
2		See Assy Dwg	4-40 X 1/4 Machine screw PH SS	Building Fasteners	PMSSS 440 0025 PH

# Appendix A

# TLV320AIC20K/24K EVM Schematic

The TLV320AIC20K/24KEVM schematics are provided on the following pages.

A-1

